

HEIDENHAIN



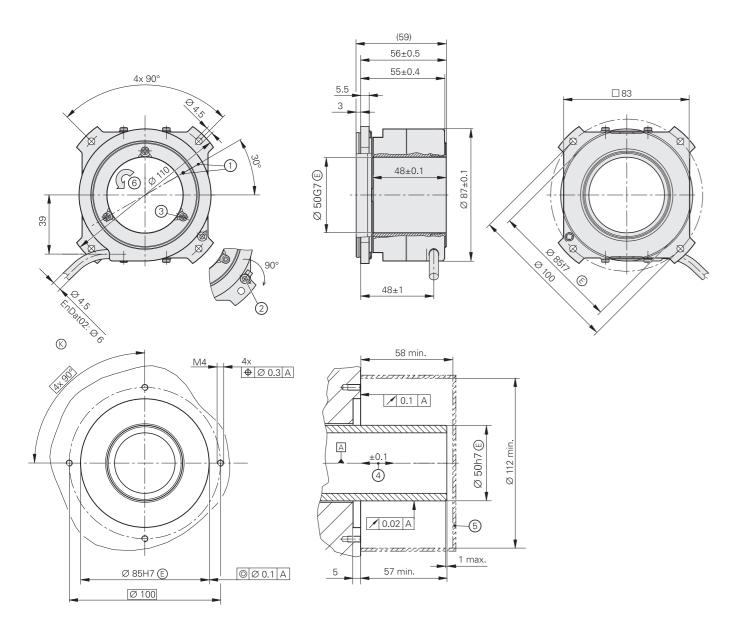
Product Information

ECN 2000

Absolute Angle Encoders with Integral Bearing

ECN 2000

- Mounted stator coupling
- Hollow through shaft: Ø 50 mm
- System accuracy: ±10"





- □ = Bearing of mating shaft○ = Required mating dimensions
- $1 = Marking of the 0^{\circ} position \pm 15^{\circ}$
- 2 = Release the mounting aid by turning prior to initial operation; width A/F 3 3 = Width A/F 3 (3 x 120°); tightening torque: 2.5 Nm + 0.5 Nm
- 4 = Stated tolerance contains the mounting tolerances and thermal expansion; no dynamic movement permitted 5 = Comply with protection against contact (EN 60529)
- 6 = Direction of shaft rotation for the output signals in accordance with the interface description

	ECN 2110	ECN 2180	ECN 2190F	ECN 2190M			
Measuring standard	DIADUR circular scale with absolute and incremental track (2048 lines)						
System accuracy	±10"						
Position error per signal period	≤ ±1.5"						
Interface	EnDat 2.2		Fanuc Serial Interface αi Interface	Mitsubishi High Speed Interface			
Ordering designation*	EnDat22	EnDat02	Fanuc05	Mit03-4			
Position values per rev.	33554432 (25 bits); with Fanuc α Interface 8388608 (23 bits)						
Electrically permissible speed	≤ 3000 rpm for continuous position value						
Clock frequency	≤ 16 MHz	≤ 2 MHz	-				
Calculation time t _{cal}	≤ 6 µs	≤ 9 µs	-				
Incremental signals	_	∼1 V _{PP}	-				
Cutoff frequency –3 dB	-	≥ 400 kHz	-				
Electrical connection*	Cable (1 m) with 8-pin M12 coupling (male)	Cable (1 m) with 17-pin M23 coupling (male)	Cable (1 m) with or without an 8-pin M12 coupling (male)				
Cable length ¹⁾	≤ 150 m		≤ 50 m ≤ 30 m				
Supply voltage	DC 3.6 V to 14 V						
Power consumption ²⁾ (maximum)	3.6 V: ≤ 0.7 W 14 V: ≤ 0.8 W						
Current consumption (typical)	5 V: 100 mA (without load)						
Shaft	Hollow through shaft, 50 mm						
Mech. permissible speed	≤ 3000 rpm						
Starting torque (at 20 °C)	≤ 0.2 Nm						
Moment of inertia of rotor	220 · 10 ⁻⁶ kgm ²						
Permiss. axial motion of measured shaft	±0.1 mm						
Natural frequency	≥ 1000 Hz						
Vibration 55 Hz to 2000 Hz Shock 6 ms	\leq 100 m/s ² (EN 60068-2-6) \leq 200 m/s ² (EN 60068-2-27)						
Operating temperature	Moving cable: -10 °C to 60 °C Stationary cable: -20 °C to 60 °C						
Protection EN 60529	IP64						
Mass	≈ 0.7 kg						

^{*} Please select when ordering

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¹⁾ With HEIDENHAIN cable

²⁾ See *General electrical information* in the *Interfaces of HEIDENHAIN Encoders* brochure

Mounting

The **ECN 2000** angle encoders have an integral bearing, a hollow shaft and a stator-side coupling. The measured shaft is directly connected to the shaft of the angle encoder.

The circular scale is firmly connected to the hollow shaft. The scanning unit rides on the shaft on ball bearings and is connected to the housing with a stator-side coupling. The stator coupling and the sealing design greatly compensate for axial and radial mounting errors without restricting functionality or accuracy. This therefore simplifies mounting. During angular

acceleration of the shaft, the coupling must absorb only the torque resulting from friction within the bearing. Angle encoders with a stator coupling therefore exhibit excellent dynamic performance.

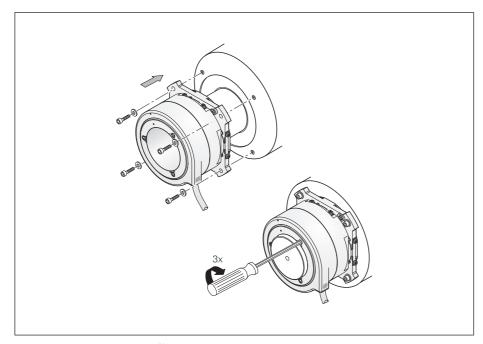
Mounting

The housing of the ECN 2000 is firmly connected to the mounting surface of the machine component via a mounting flange and a centering collar. For coupling to the shaft, the ECN with its hollow shaft is press-fitted onto the motor shaft and clamped on the rotor side with three eccentric clamps.

Materials to be used for mounting the ECN 2000

The machine shaft and the fastening components must be made of steel. The material must exhibit a coefficient of thermal expansion of $\alpha = (10 \text{ to } 16) \cdot 10^{-6} \text{ K}^{-1}$ Additionally, the material must meet the following specifications:

- For a hollow shaft connection $R_m \ge 650 \text{ N/mm}^2$ $R_{p0.2} \ge 370 \text{ N/mm}^2$
- For a housing connection $R_{p0.2} \ge 370 \text{ N/mm}^2$



Mounting an ECN 2000 with a \varnothing 50 mm hollow shaft

Electrical connection

EnDat connecting cable without incremental signals

PUR adapter cables and connecting cable Ø 6 mm; $2(2 \times 0.09 \text{ mm}^2) + 2(2 \times 0.16 \text{ mm}^2)$ $A_P = 2 \times 0.16 \text{ mm}^2$					
Adapter cable with 8-pin M12 connector (female) and 15-pin D-sub connector (female)		1036521-xx			
Adapter cable with 15-pin connector (female) and 15-pin D-sub connector (male)		1036526-xx			
Connecting cable with 8-pin M12 connector (female) and 8-pin M12 coupling (male)	<u></u>	1036372-xx			

EnDat adapter cable with incremental signals

PUR adapter cables and connecting cable Ø 8 mm; $4(2 \times 0.16 \text{ mm}^2) + 4 \times 0.5 \text{ mm}^2 + 4 \times 0.16 \text{ mm}^2$) $A_P = 0.5 \text{ mm}^2$						
Adapter cable with 17-pin M23 connector (female) and 15-pin D-sub connector (female)		332115-xx				
Adapter cable with 17-pin M23 connector (female) and 15-pin D-sub connector (male)		324544-xx				
Connecting cable with 17-pin M23 connector (female)		309778-xx				

Fanuc/Mitsubishi connecting cable

PUR connecting cable	Ø 6 mm; 2(2 × 0.0	109 mm^2) + 2(2 × 0.16 mm ²)	$A_P = 2 \times 0.16 \text{ mm}^2$	Fanuc	Mitsubishi
Fully assembled with 8-pin M12 connector (femal 8-pin M12 coupling (male)	le) and	<u></u>	==	1036372-xx	

A_P: Cross section of power supply lines

HEIDENHAIN

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This Product Information document supersedes all previous editions, which thereby become invalid. The basis for ordering from HEIDENHAIN is always the Product Information document edition valid when the order is placed.



(More information:

Comply with the requirements described in the following documents to ensure correct and intended operation:

- Brochure: Angle Encoders with Integral Bearing
- Brochure: Interfaces of HEIDENHAIN Encoders
- 1078628-xx • Brochure: Cables and Connectors 1206103-xx

591109-xx

For brochures and Product Information documents, visit www.heidenhain.com.

Ø: Cable diameter (for bend radii, see the Interfaces of HEIDENHAIN Encoders brochure)

For more cables, see the brochure Angle Encoders with Integral Bearing.